

Senior Design Team 517













Joshua Jones **Robotics Engineer**

Ryan Dingman Controls Engineer

Matthew Schrold Test Engineer

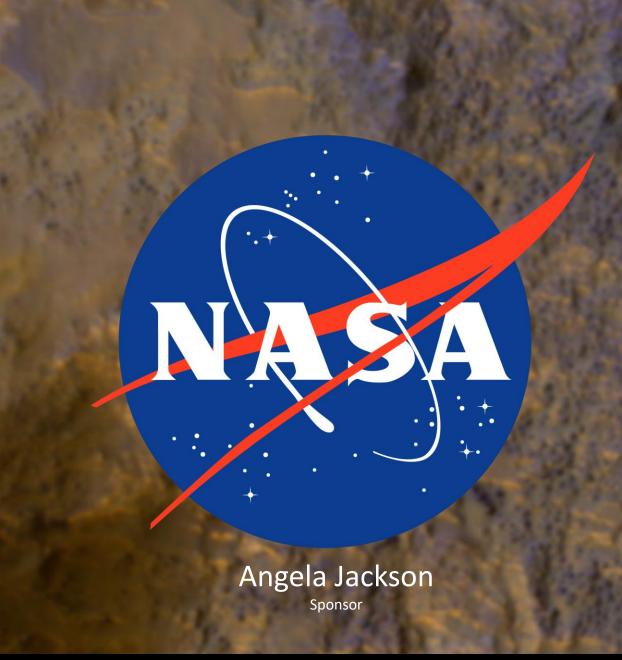
Justin Bomwell Software Engineer

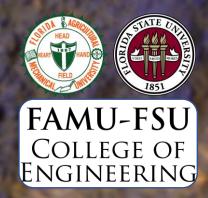
Victor Prado Design Engineer

Kalin Burnside Power Systems Engineer













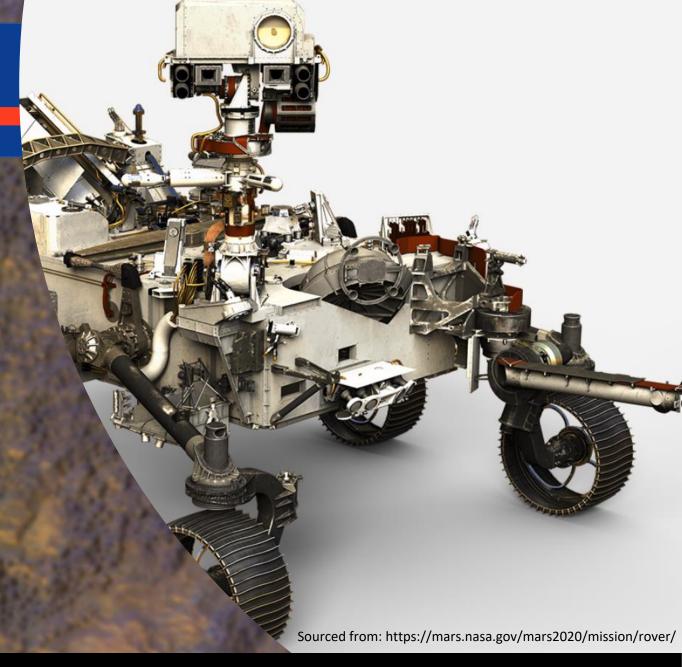


Dr. Camilo Ordóñez



Objective

The objective of this project is to onboard a sample from the environment, then manipulate it within the rover so that testing instruments can perform all necessary tests on the sample.





In 2015, NASA confirmed that water flows on Mars.



Could there also be/have been life on Mars?





Signs of life could be in the form of fossils.



Samples must be brought back to Earth to study.

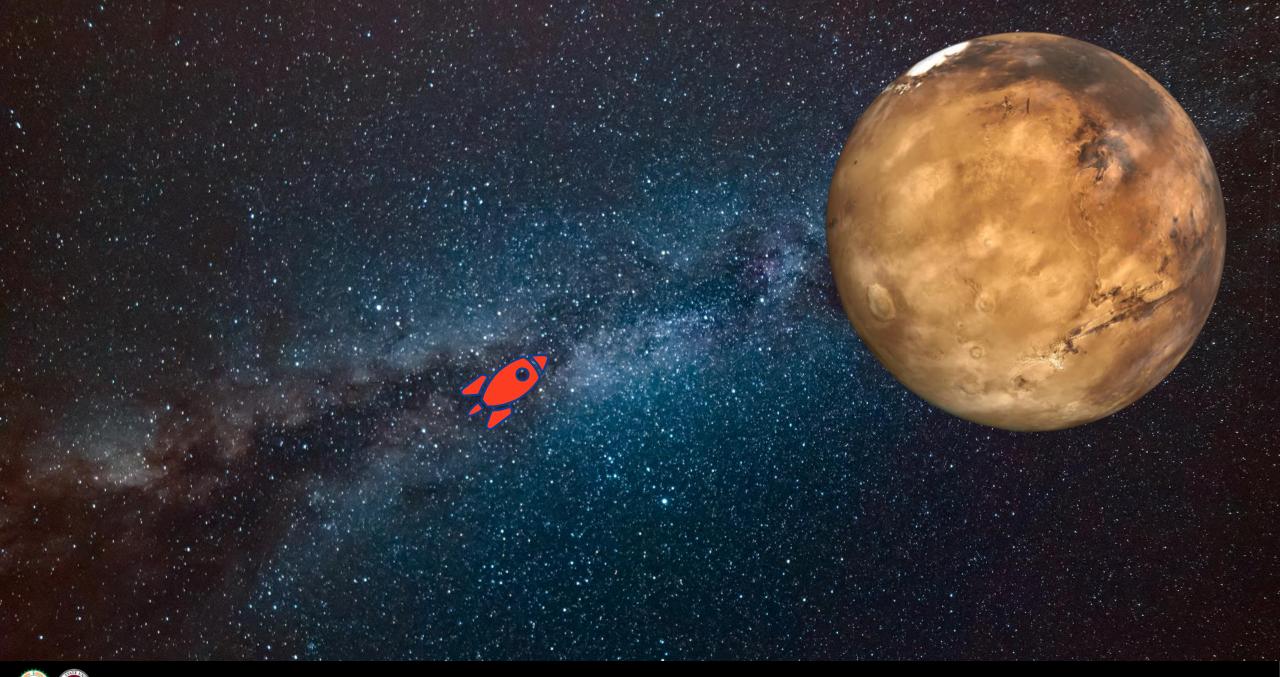


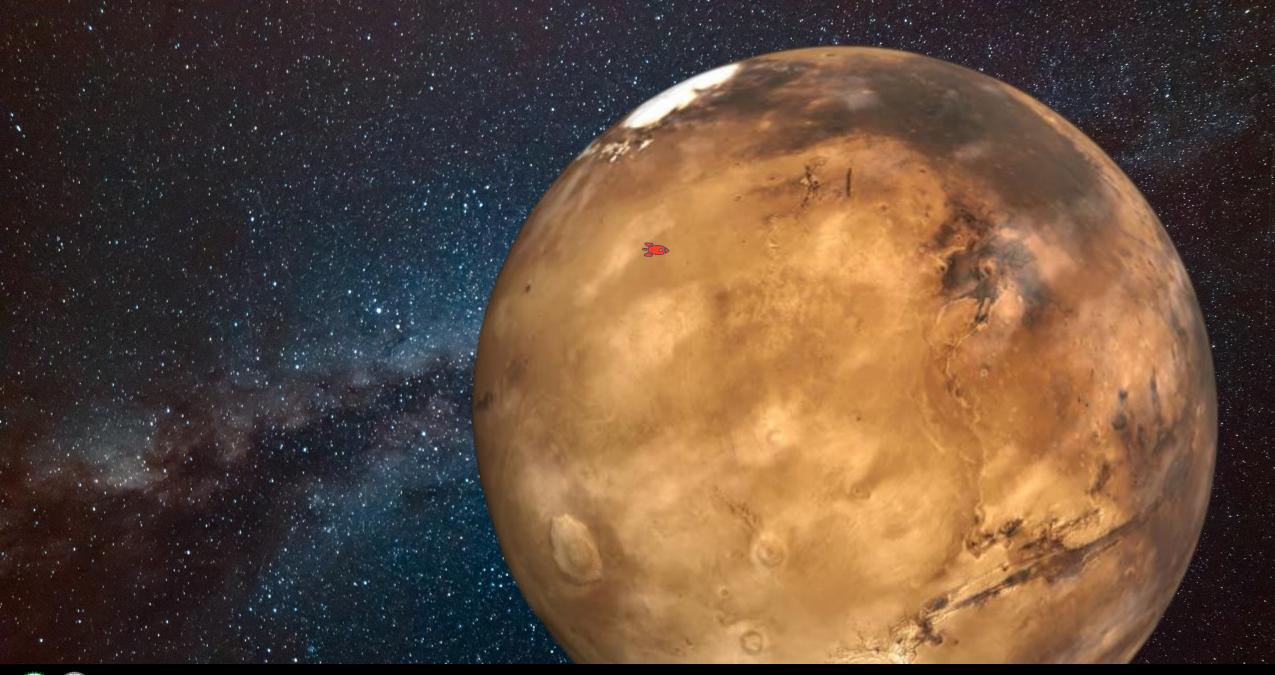


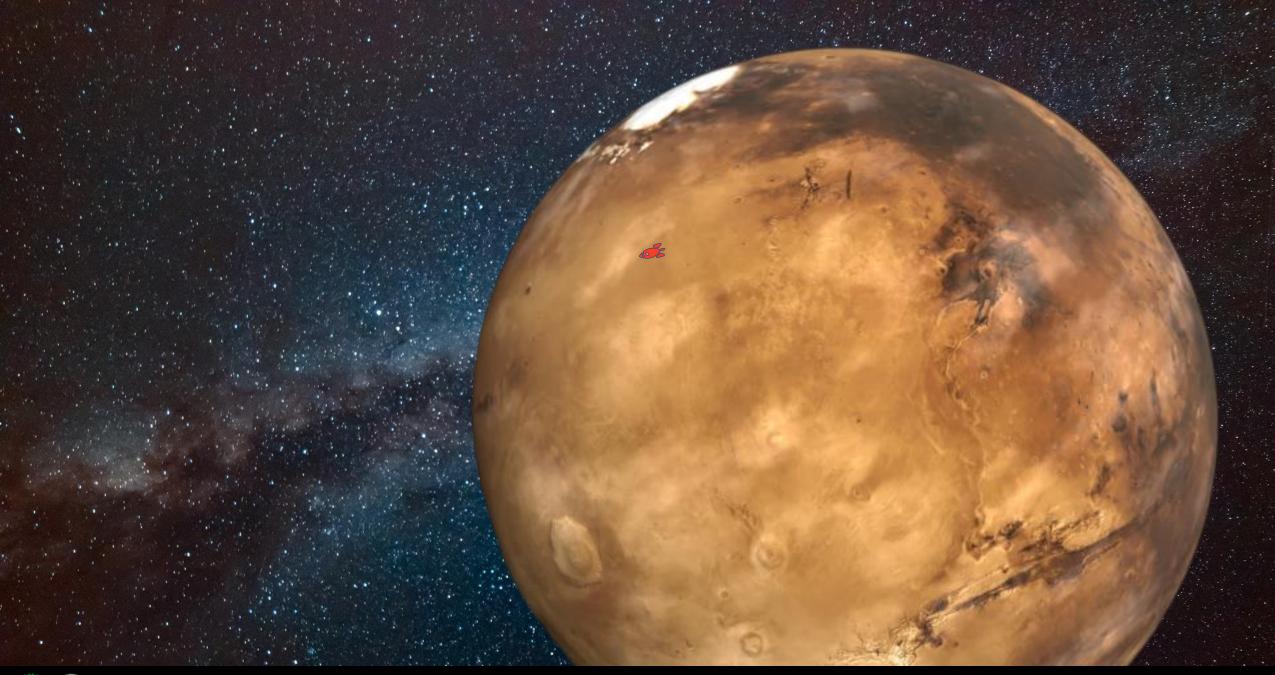








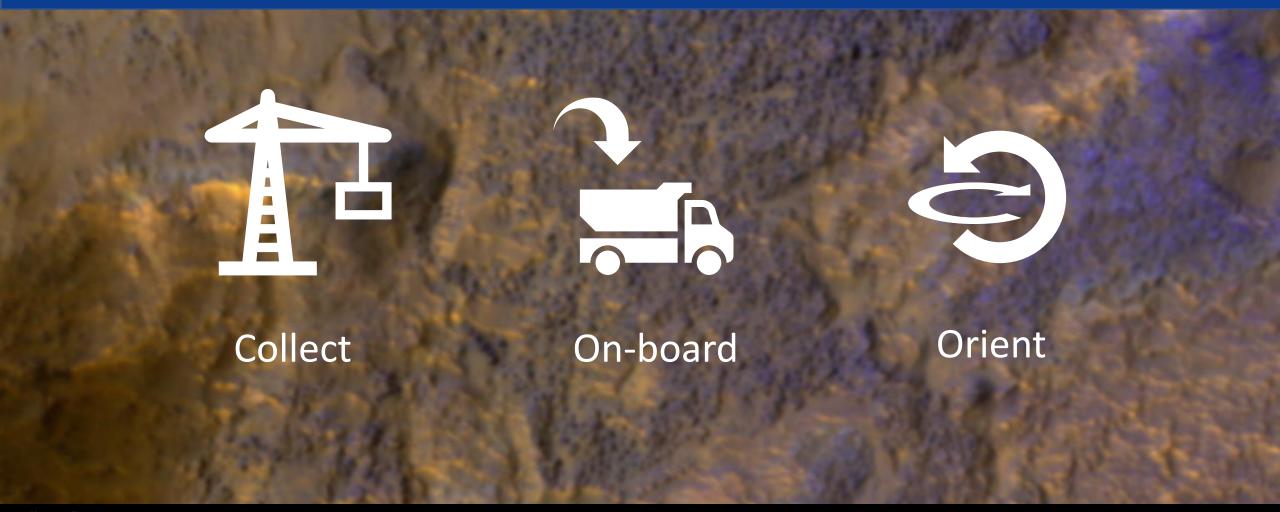








Key Goals



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Assumptions

Device will be part of a larger rover system, which will provide power

The rover will be stationary during sample collection, loading, and orienting

Air resistance will be negligible

Samples will be free of sand or dirt



Sourced from: https://mars.nasa.gov/mars2020/mission/rover/

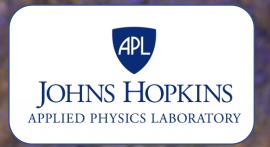
Markets

Primary Market:



Secondary Markets:









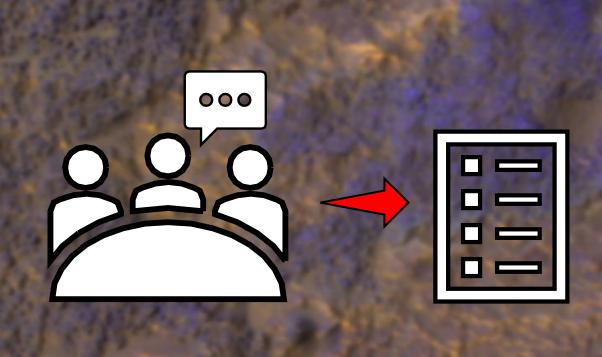


Customer Needs

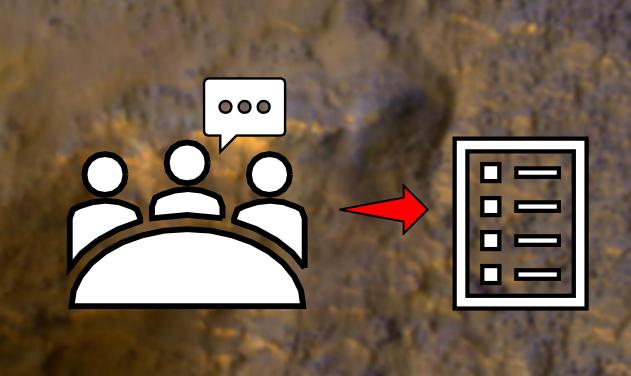
Transports the sample on-board

Manipulates the sample vertically and rotationally

Allow stationary sensors access to any surface location on the sample



Customer Needs

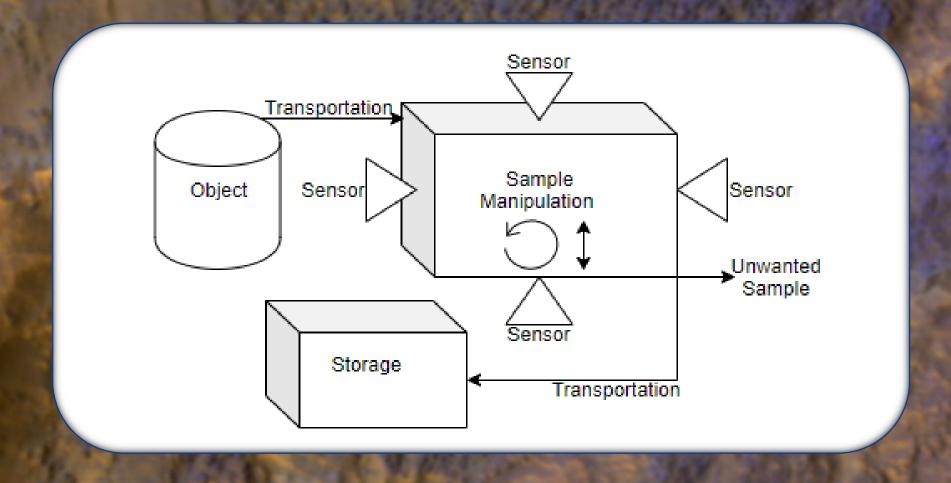


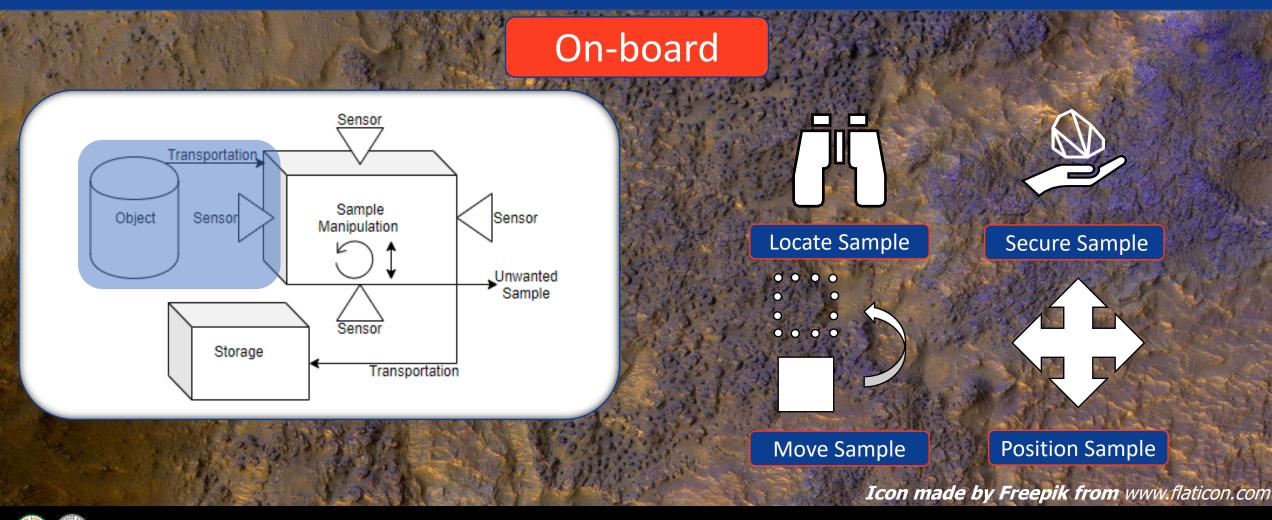
Accommodates varying sample sizes

Stores samples in a separate location

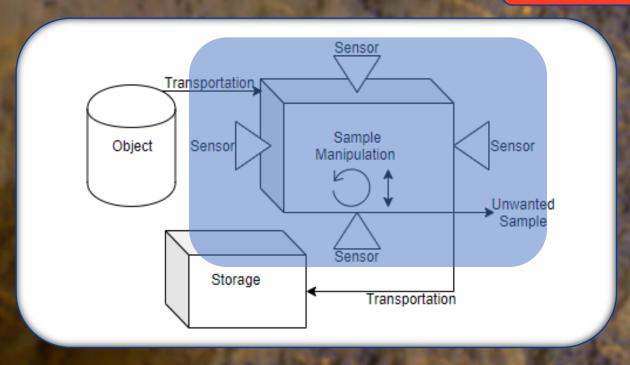
Light weight

Allows for the integration of power systems with the rover





Orient





Import Sample



Stabilize Sample

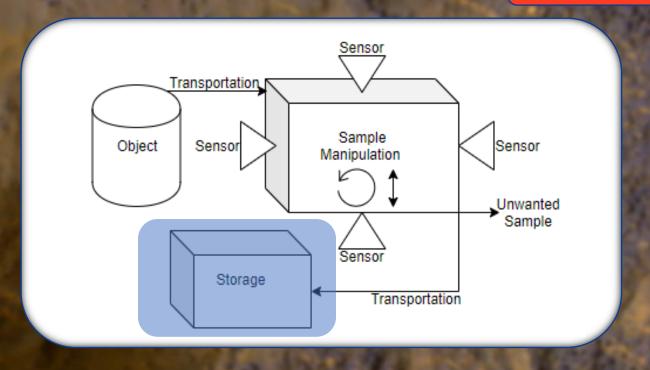


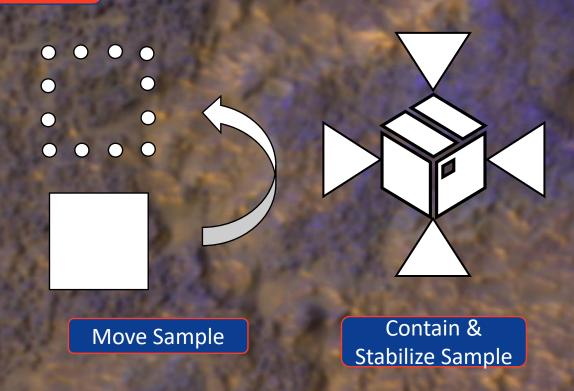
Rotate Sample

Icon made by Freepik from www.flaticon.com

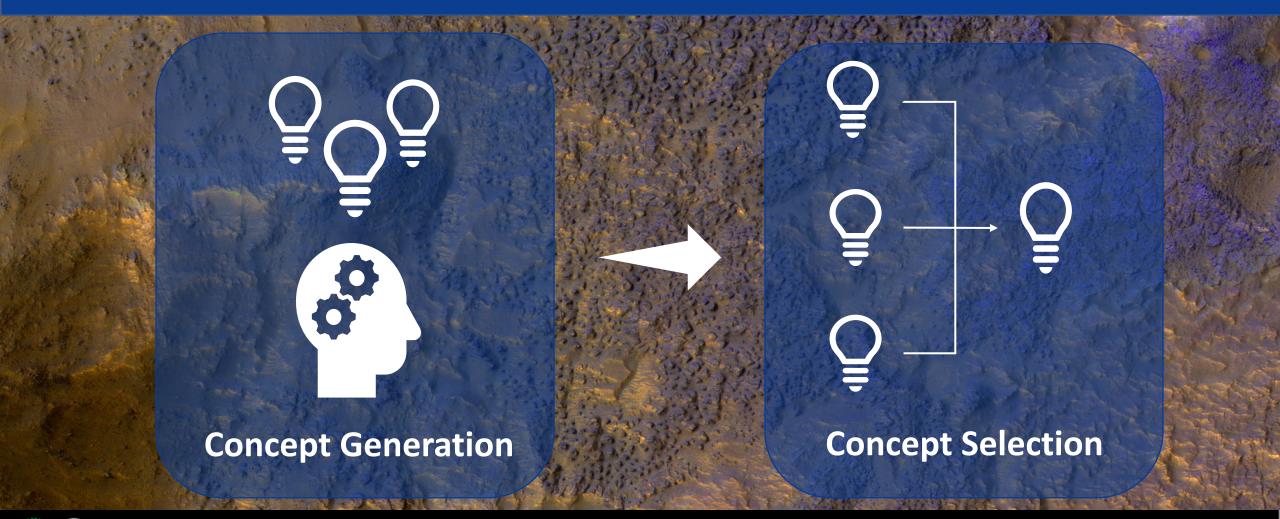


Store





Future Work



Gantt Chart for Deliverables

						CONTRACTOR STATE				CALL AND COMPACED BY				A STATE OF THE STA			-			
Tasks	Completion	August		September			October				November			December						
Advisor Meet and Greet	100%																			
Project Charter	100%																			
Work Breakdown Structure	100%																			
Sponsor Meet and Greet	0%																			
Customer Needs	100%																			
Functional Decomposition	100%																			
VDR 1	Ongoing																			
Targets	Ongoing																			
Concept Generation	Ongoing																			
Concept Selection	0%																			
VDR 2	0%																			
Bill of Materials (BOM)	0%																			
Risk Assessment	0%																			
Spring Project Plan	0%																			
VDR 3	0%																			
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- Complete

- Outstanding

- Indeterminate

- Ongoing

References

- 1. https://mars.nasa.gov/mars2020/mission/rover/
- 2. https://www.nasa.gov/centers/marshall/news/background/facts/astp.html



Team 517 Sample On-Boarding and Orientation

October 10, 2019

Joshua Jones Ryan Dingman **Justin Bomwell** Matthew Schrold Victor Prado Kalin Burnside

Project Background

Project Scope

Customer Needs

Functional Decomposition



Collect



On-board



Orient



