

Human Powered Vehicle (HPV)

13 November 2018



TEAM MEMBERS

Tyler Schilf **Tristan Enriquez** **Jacob Thomas** **Kyler Marchetta**



Project Manager



Steering Engineer



Powertrain Engineer



Ergonomics Engineer



Project Review



FAMU-FSU
COLLEGE OF ENGINEERING

Competition Objectives



Design

- Methodology
- Testing and Analysis
- Safety
- Aesthetics



Speed

- Timed race
- Top speed
- Men and Women



Endurance

- Agility, Utility and Durability
- Obstacles
- Inclines and Declines
- Tight turning

Mission Objective:

Produce a vehicle for the Human Powered Vehicle Competition (HPVC) that a rider will mechanically power and control through their input force.

Project Budget: **\$2,000**

Competition Objectives



Design

- Methodology
- Testing and Analysis
- Safety
- Aesthetics



Speed

- Timed race
- Top speed
- Men and Women



Endurance

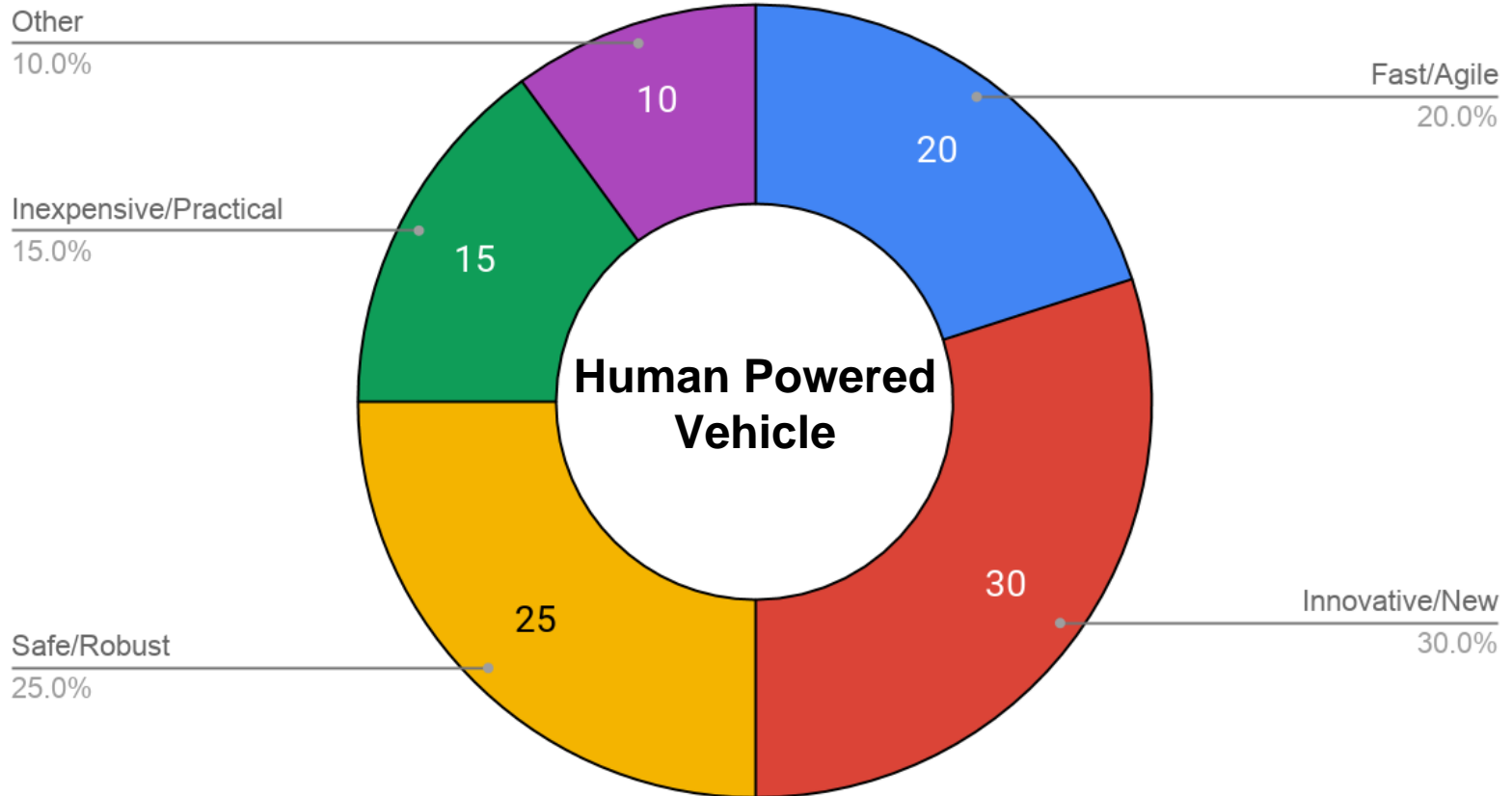
- Agility, Utility and Durability
- Obstacles
- Inclines and Declines
- Tight turning

Mission Objective:

Produce a vehicle for the Human Powered Vehicle Competition (HPVC) that a rider will mechanically power and control through their input force.

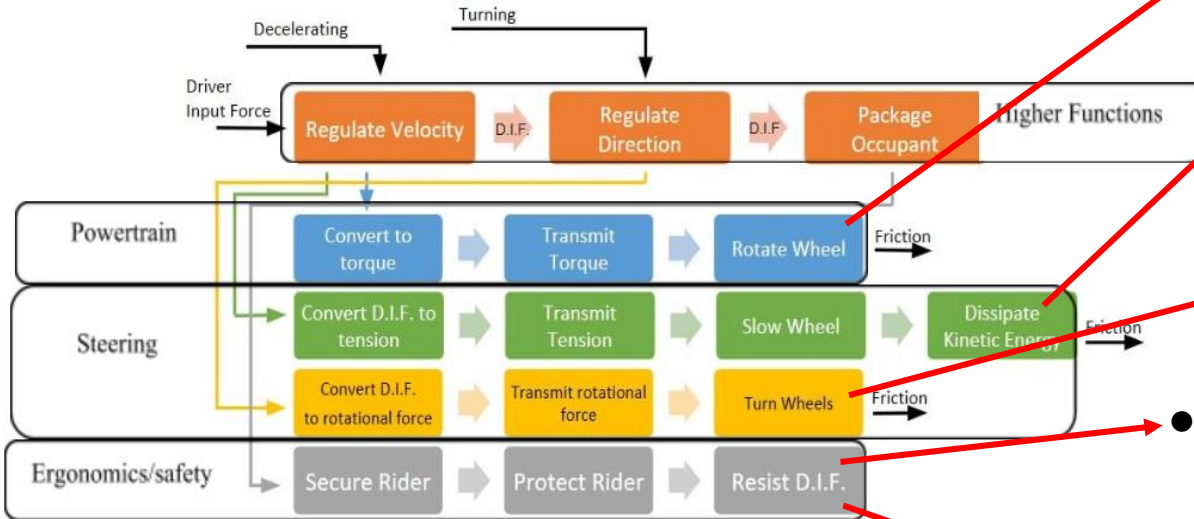
Project Budget: **\$2,000**

Customer Needs



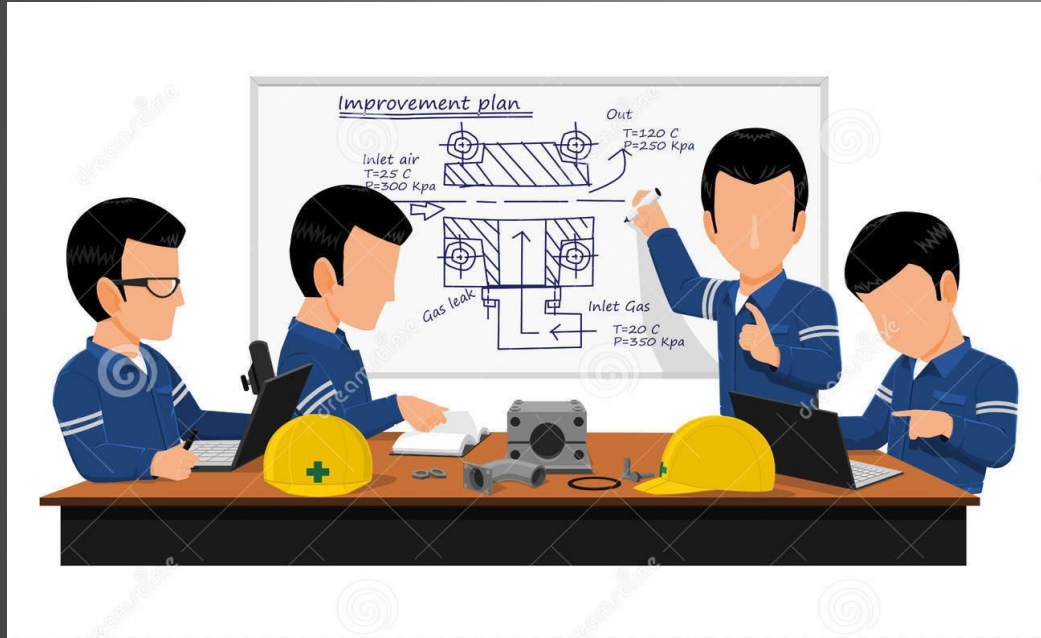
Functional Breakdown

Targets/Metrics



- Top speed of 40 km/h
- Brake in 4 m at a speed of 25 km/h
- Turning radius of 6.0 m
- Supports 2670 N applied to top roll protection system (rps) in the event of a rollover
- Supports 1330 N applied to roll bar at shoulder height

Concept Generation



Concept Generation

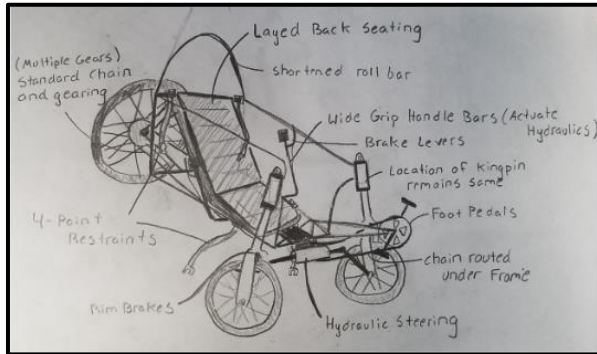


Figure 1: Concept #42

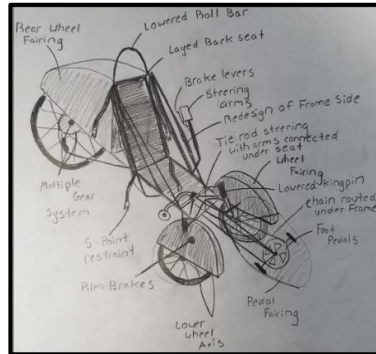


Figure 2: Concept #85

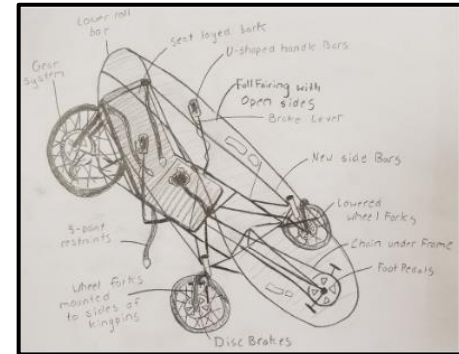


Figure 3: Concept #92

Concept #42

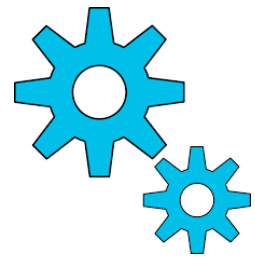
- Push/Pull lever actuate rim brakes
- Hydraulic Steering
- No fairing

Concept #85

- Hand lever steering
- Brake lever on handle actuate rim brakes
- Nose, front, and rear wheel fairings

Concept #92

- Hand lever steering
- Brake lever on handle actuates disc brake
- Full fairing with open sides



Concept Generation

The next three most plausible concepts for comparison..

Concept #24

- Disc brakes
- Partial Fairing
- Tie rod steering
- 3 point safety harness

Concept #58

- Direct tie rod steering
- Belt and CVT
- Car strap restraint
- Leaf spring suspension
- Disc Brakes

Concept #87

- Rack and pinion steering
- Steering column with wheel
- Partial fairing
- Hand lever brake actuation

Concept Selection



House of Quality Chart (HOQ)

HOUSE OF QUALITY																				
		Engineering Characteristics																		
Units		MPa	m/s	m	m	kg	m^2	W	W	Cd	m	m	N	N	N	s	deg	USD	N/A	m^3
Customer Requirements	Importance Weight Factor	Strength	Speed	Braking Distance	Turning Radius	Weight	Foot Print Area	Cruising Power on 0% Grade	Cruising Power > 0% Grade	Drag Coefficient	Height	Length	Brake Force	Pedal Force	Steering Force	Enter/Exit Time	Rider Position	Cost	Complexity	Rider Cabin Space
Protects Rider/Robust	9	9	0	9	9	1	0	0	0	0	3	0	1	0	1	1	3	1	3	1
Turns Quickly	7	0	1	1	9	9	3	0	0	1	3	3	1	0	9	0	1	0	1	0
Is lightweight	5	3	9	9	3	9	1	3	9	0	1	1	0	3	3	0	0	9	3	0
Visually Appealing	1	1	0	0	0	0	0	0	0	3	3	3	0	0	0	1	9	3	9	3
Comfortability	5	1	0	0	0	0	1	1	1	3	3	3	3	3	3	3	5	3	3	9
Affordability	2	9	3	3	0	3	0	0	0	9	0	0	0	1	0	0	0	9	9	0
High Top Speed	5	0	9	0	0	9	0	3	3	9	1	1	0	3	1	0	1	9	3	0
Low Drag	1	0	9	0	1	0	9	9	3	9	3	3	0	1	0	3	1	9	9	3
Brakes Quickly	8	0	1	9	1	9	1	0	0	3	1	1	9	0	0	0	0	9	9	0
Easily Maintained	2	0	0	0	0	3	0	0	0	3	0	0	0	0	0	0	0	9	9	1
Raw Score (1153)		120	120	211	168	246	48	44	68	127	87	60	103	48	107	28	74	234	205	62
Relative Weight %		5.556	5.556	9.769	7.778	11.389	2.222	2.037	3.148	5.880	4.028	2.778	4.769	2.222	4.954	1.296	3.426	10.833	9.491	2.870
Rank Order		7	7	3	5	1	16	18	13	6	11	15	10	16	9	19	12	2	4	14

Table 1: House of Quality

House of Quality Chart (HOQ)

		HOUSE OF QUALITY																		
		Engineering Characteristics																		
Units		MPa	m/s	m	m	kg	m^2	W	W	Cd	m	m	N	N	N	s	deg	USD	N/A	m^3
Customer Requirements	Importance Weight Factor	Strength	Speed	Braking Distance	Turning Radius	Weight	Foot Print Area	Cruising Power on 0% Grade	Cruising Power >0% Grade	Drag Coefficient	Height	Length	Brake Force	Pedal Force	Steering Force	Enter/Exit Time	Rider Position	Cost	Complexity	Rider Cabin Space
Protects Rider/Robust	9	9	0	9	9	1	0	0	0	0	3	0	1	0	1	1	3	1	3	1
Turns Quickly	7	0	1	1	9	9	3	0	0	1	3	3	1	0	9	0	1	0	1	0
Is lightweight	5	3	9	9	3	9	1	3	9	0	1	1	0	3	3	0	0	9	3	0
Visually Appealing	1	1	0	0	0	0	0	0	0	3	3	3	0	0	0	1	9	3	9	3
Comfortability	5	1	0	0	0	0	1	1	1	3	3	3	3	3	3	3	5	3	3	9
Affordability	2	9	3	3	0	3	0	0	0	9	0	0	0	1	0	0	0	9	9	0
High Top Speed	5	0	9	0	0	9	0	3	3	9	1	1	0	3	1	0	1	9	3	0
Low Drag	1	0	9	0	1	0	9	9	3	9	3	3	0	1	0	3	1	9	9	3
Brakes Quickly	8	0	1	9	1	9	1	0	0	3	1	1	9	0	0	0	0	9	9	0
Easily Maintained	2	0	0	0	0	3	0	0	0	3	0	0	0	0	0	0	0	9	9	1
Raw Score (1153)		120	120	211	168	246	48	44	68	127	87	60	103	48	107	28	74	234	205	62
Relative Weight %		5.556	5.556	9.769	7.778	11.389	2.222	2.037	3.148	5.880	4.028	2.778	4.769	2.222	4.954	1.296	3.426	10.833	9.491	2.870
Rank Order		7	7	3	5	1	16	18	13	6	11	15	10	16	9	19	12	2	4	14

Table 1: House of Quality



Initial Pugh Chart

Six concepts compared to the GT20

“A carefully engineered, lightweight frame, low rolling resistance tires, and an efficient drivetrain...”

Figure 4: GT20 Recumbent Trike

Engineering Characteristics	Datum Comparison	Design Concepts Numbers					
	Green Speed GT20	42	85	92	87	58	24
Weight	Datum	-	-	-	-	-	-
Cost	Datum	-	+	+	-	-	+
Braking Distance	Datum	-	-	S	-	S	S
Complexity	Datum	-	+	S	-	-	S
Turning Radius	Datum	+	S	S	+	S	S
Total (+)		1	2	1	1	0	1
Total (-)		4	2	1	4	3	1

Table 2: Initial Pugh Chart



Initial Pugh Chart

Six concepts compared to the GT20

Figure 4: GT20 Recumbent Trike

	Datum Comparison	Design Concepts Numbers					
Engineering Characteristics	Green Speed GT20	42	85	92	87	58	24
Weight	Datum	-	-	-	-	-	-
Cost	Datum	-	+	+	-	-	+
Braking Distance	Datum	-	-	S	-	S	S
Complexity	Datum	-	+	S	-	-	S
Turning Radius	Datum	+	S	S	+	S	S
Total (+)		1	2	1	1	0	1
Total (-)		4	2	1	4	3	1

Table 2: Initial Pugh Chart



Initial Pugh Chart

Six concepts compared to the GT20

New Datum

Figure 4: GT20 Recumbent Trike

	Datum Comparison	Design Concepts Numbers					
Engineering Characteristics	Green Speed GT20	42	85	92	87	58	24
Weight	Datum	-	-	-	-	-	-
Cost	Datum	-	+	+	-	-	+
Braking Distance	Datum	-	-	S	-	S	S
Complexity	Datum	-	+	S	-	-	S
Turning Radius	Datum	+	S	S	+	S	S
Total (+)		1	2	1	1	0	1
Total (-)		4	2	1	4	3	1

Table 2: Initial Pugh Chart

Final Pugh Chart

	Datum Comparison	Design Concepts Numbers	
Engineering Characteristics	24	85	92
Weight	Datum	-	-
Cost	Datum	S	-
Braking Distance	Datum	-	S
Complexity	Datum	-	-
Turning Radius	Datum	S	S
Total (+)		0	0
Total (-)		3	3

Table 3: Final Pugh Chart

Final Pugh Chart

Cost is Heavily Weighted
(number 2 from HOQ)

	Datum Comparison	Design Concepts Numbers	
Engineering Characteristics	24	85	92
Weight	Datum	-	-
Cost	Datum	S	-
Braking Distance	Datum	-	S
Complexity	Datum	-	-
Turning Radius	Datum	S	S
Total (+)		0	0
Total (-)		3	3

Table 3: Final Pugh Chart

Final Pugh Chart

	Datum Comparison	Design Concepts Numbers	
Engineering Characteristics	24	85	92
Weight	Datum	-	-
Cost	Datum	S	-
Braking Distance	Datum	-	S
Complexity	Datum	-	-
Turning Radius	Datum	S	S
Total (+)		0	0
Total (-)		3	3

Table 3: Final Pugh Chart

Analytical Hierarchy Process (Concepts 24 and 85)

Table 4: Weight Matrix

	Weight	Cost	Braking Distance	Complexity	Turning Radius	Criteria Weights
Weight	0.045	0.021	0.059	0.161	0.032	0.064
Cost	0.225	0.107	0.176	0.226	0.045	0.156
Braking Distance	0.405	0.321	0.529	0.290	0.674	0.444
Complexity	0.009	0.015	0.059	0.032	0.025	0.028
Turning Radius	0.315	0.535	0.176	0.290	0.225	0.308
Totals	1.000	1.000	1.000	1.000	1.000	1.000

Table 5: Alternative Design Weight

Matrix	Final Rating Matrix	
	Disc Brakes	Rim Brakes
Weight	0.83	0.17
Cost	0.1	0.9
Turning	0.75	0.25
Braking	0.88	0.13
Complexity	0.17	0.83

Table 6: AHP Decision Results

Results	
Concept	Alternative Value
Concept 24	0.48
Concept 85	0.52

Analytical Hierarchy Process (Concepts 24 and 85)

Table 4: Weight Matrix

	Weight	Cost	Braking Distance	Complexity	Turning Radius	Criteria Weights
Weight	0.045	0.021	0.059	0.161	0.032	0.064
Cost	0.225	0.107	0.176	0.226	0.045	0.156
Braking Distance	0.405	0.321	0.529	0.290	0.674	0.444
Complexity	0.009	0.015	0.059	0.032	0.025	0.028
Turning Radius	0.315	0.535	0.176	0.290	0.225	0.308
Totals	1.000	1.000	1.000	1.000	1.000	1.000

Table 5: Alternative Design Weight

Matrix	Final Rating Matrix	
	Disc Brakes	Rim Brakes
Weight	0.83	0.17
Cost	0.1	0.9
Turning	0.75	0.25
Braking	0.88	0.13
Complexity	0.17	0.83

Table 6: AHP Decision Results

Results	
Concept	Alternative Value
Concept 24	0.48
Concept 85	0.52

Final Decision (Concept 85)

Features:

- 5-Point Restraint
- 10 speed transmission
- Wide Grip Handlebar Steering
- Laid Back Rider Position
- Minimal Fairings
- Adjustable Pedal Mount
- Front Wheel Rim Brakes

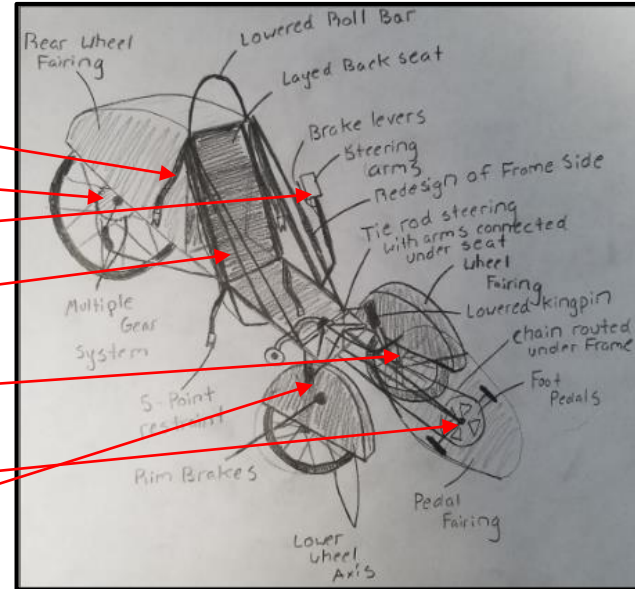
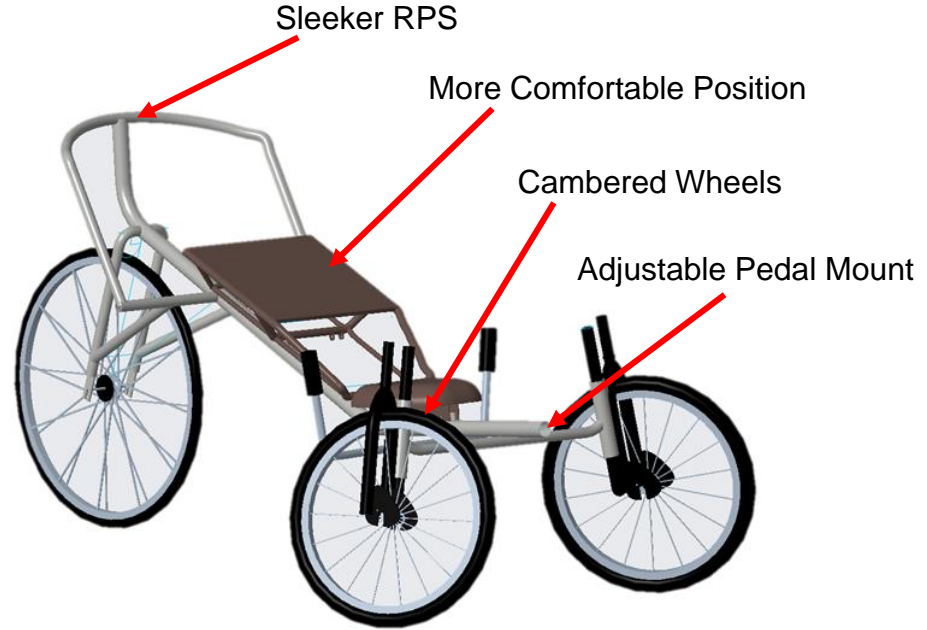


Figure 5: Rough Conceptual Sketch

Old Frame



New Frame



Looking Ahead...

November 22nd

December 2nd

December 8th

December 14th

**Testing and Analysis
of New Frame**

**Purchasing of
Materials to
Fabricate the New
Frame**

**Detailed Design of
Concept 85**

Spring Project Plan

References

1. ASME (2018). *Rules for the 2018 Human Powered Vehicle Challenge*. Retrieved from: [https://www.asme.org/events/competitions/human-powered-vehicle-challenge-\(hpvc\)](https://www.asme.org/events/competitions/human-powered-vehicle-challenge-(hpvc))
2. Backcountry Recumbent Bicycles. (2018) Retrieved from: <http://www.backcountryrecumbentcycles.com/shop/greenspeed-gt20/>
3. Bauer, B., Bohne, E., Lanier, P., MacDonnell, G., & Rodriguez, M. (2017). *Virtual Design Review 4 Team 20*. Retrieved from: https://ww2.eng.famu.fsu.edu/me/senior_design/2018/team20/4thVDR.pdf

Questions?

Tyler Schilf Tristan Enriquez Jacob Thomas Kyler Marchetta



Project Manager



Steering Engineer



Powertrain Engineer



Ergonomics Engineer





Project Timeline

Human Powered Vehicle

Team 512
Tyler Schif

SIMPLE GANTT CHART by Vertex42.com
<https://www.vertex42.com/ExcelTemplates/simple-gantt-chart.html>

Project Start: Sun, 9/9/2018
Display Week: 7

