

# No Contact Gap Measurement Team 13: Samuel Giaquinto, Matt Nagy, Forrest Parker Sponsor: General Capacitors, Dr. Jim P. Zheng

## Summary

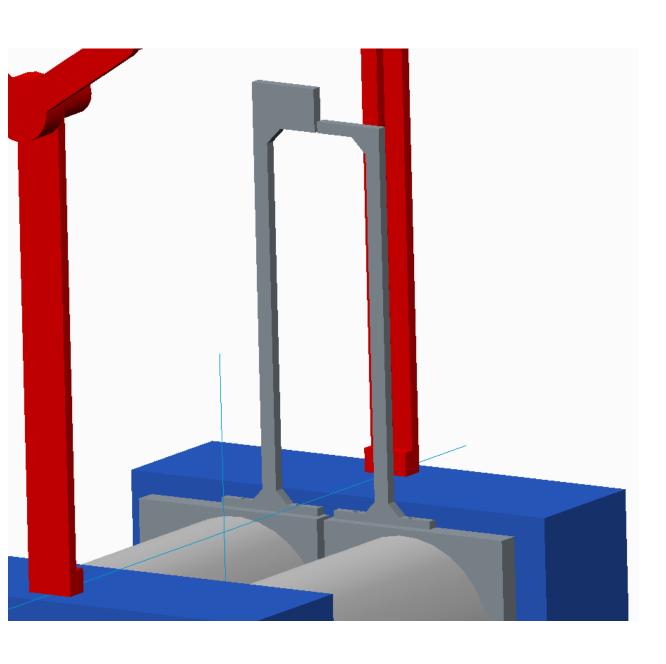
- General Capacitor currently gaps their hot rolling machine using feeler gages that scratch or dent the expensive rollers.
- Lasers and high resolution optics designs were too expensive and non practical
- Final Design involves rigidly mounting arms to the roller positioning blocks and measuring the representative gap with inductance sensors.



# Background

- Battery materials are pushed through the rollers and are used for different calculations and experiments.
- Finite gap needed to determine the capacitance of the certain material.

# Final Design Schematic





#### Constraints

- 80 200 micron gap • Non-contact
- 2 micron resolution • Gap length of 30 cm
- \$2,000 budget provided by sponsor

## Inductance Sensor

- Keyence EX-422V inductance displacement sensor
- Resolution of 2 μm
- Working distance of 0-10 mm.
- 20 displays per second









#### Microcontroller

Arduino UNO R3

- 14 digital input output pins
- 16 MHz crystal oscillator

Inputs:

- Roller temperature through keypad
- Inductance sensors (2) Outputs:
- Left and right gap measurements
- Calculated distance of center gap

# Future Plans

- Orders placed for sensors, microcontroller, and aluminum
- Assemble parts into working prototype and begin collecting data to calibrate gap measurement
- Expected difficulties include thermal expansion and stabilization

## Acknowledgements

Team 13 would like to thank Dr. Nikhil Gupta and our friends at A.M.E. for their contributions throughout our design process.

