

# Prototype Machine for Coating Stabilized Lithium Metal Powder



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## **Motivation:**

- Stabilized Lithium Metal Powder, also known as SLMP, is a newly developed product by FMC Lithium Corporation
- Metallic Lithium content is roughly 98%
- Particle size: Between 30-60 microns
- Density: 0.534 g/cm<sup>3</sup>
- SLMP is used as a sacrificial layer of lithium to compensate for the first-cycle capacitance loss.
- Increases the batteries performance by 5 to 15%.
- Increases the energy density by 2-4 times.
- Can be applied to pre-existing anodes





Image 1.1: (Left) Hard carbon electrode.(Right) Hard carbon electrode coated with SLMP



Image 1.2:Optical Microscope image of SLMP.

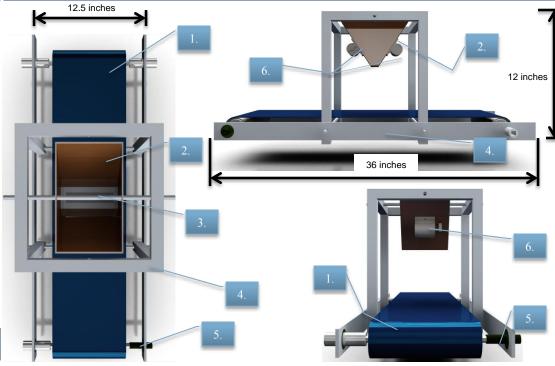
## **Purpose:**

To create a cost-effective prototype machine that can create a uniform layer of SLMP, minimum of 150µm, on a pre-existing anode.

## **Technical Approach:**

- Application of SLMP onto a pre-existing anode by utilizing vibrational forces and constant flow rates through steel wire meshes.
- SLMP will be fed into a steel funnel that will have 2 DC vibration
  motors, running at different frequencies to assist in the dispersion of
  the SLMP through the meshes placed along the length of the funnel.
  The SLMP will be dropped onto a conveyor belt which translates the
  anode sheet back and forth underneath funnel exit until fully coated.
- After this process is completed the coated anode is manually pressed to expose the inner lithium to form sacrificial layer for batteries and super capacitors.

# **Coating Machine Design:**



# **Component Breakdown**

- 1. Conveyor Belt System
- 2. Funnel
- 3. Meshes
- 4. Frame/Body
- 5. Hexagonal Adaptor
- 6. DC Vibrational Motors/ Actuators

#### **Electrical Hardware:**

- Gear Bipolar Stepper Motor
- Arduino Mega 2560 R3
- 12 V power Supply
- 12 V DC Vibration Motors: (1)-3000 RPM and (1)-4000RPM

## **Future Recommendations:**

- Addition of a stabilizing base plate as foundation for entire prototype
- Experimentation with different funnel and support rod material
- Exploration of linear vibrational methods rather than vertical displacements
- Addition of positioning and weight sensors