OFFSHORE WIND TURBINE 02/13/2014



Team #12 Jason Davis Nicholas Smith Kevin Foppe Mark Price Margaret Gidula Matthew Price Stephen Davis

Sponsor: Dr. Jung Advisor: Dr. Kumar Instructor: Dr. Amin





JASON DAVIS

SCOPE

Objectives

- Reduce the cost
 - Autonomous navigation
 - Twin tower design
 - Dry-dock construction

Background

- Potential energy production
- Growing industry
- Costs of offshore v. land-based



BRIEF FALL SEMESTER HIGHLIGHTS

Determination of largest cost drivers

- Foundations
- Construction
- Design Innovations
 Twin tower design
 Autonomy





RECENT PROGRESS

 "Mimic" several functions of full scale design
 Separated into parts
 Anchor analysis
 Testing criteria

NICHOLAS SMITH

POTENTIAL CHALLENGES

Levels of difficulty

- Basic (propulsion, generation, stationary)
- Advanced (sensors, gps, etc.)
- Scaling limitations
- Assumptions
- Error



NICHOLAS SMITH

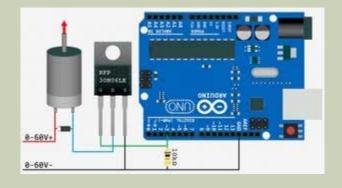
STATUS OF PROCUREMENT

• ON SCHEDULE!

Simple materials found at local stores

- Hardware
- Hobby







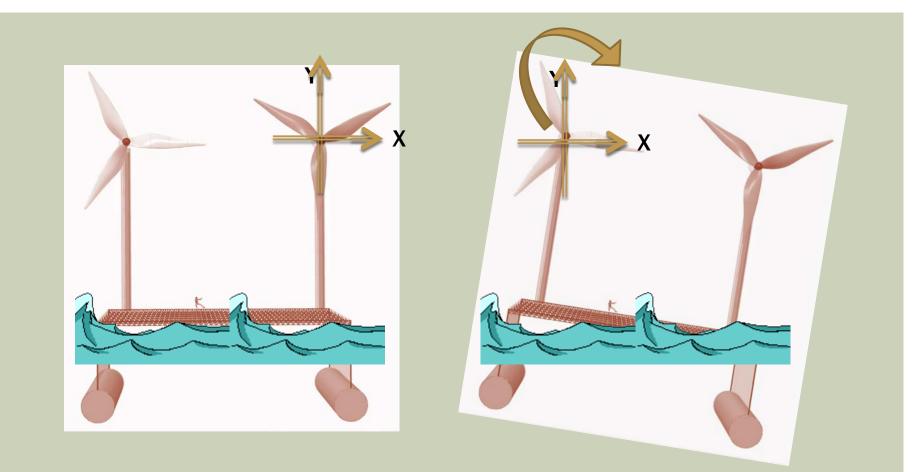
RELEVANT DATA AND ANALYSIS

- **1.** Autonomy-Static Location
- **2.** Serviceability and Rotation Limit
- **3. Efficiency of Electricity Generated**

1. AUTONOMY: BASIC PRINCIPLES AND COMPONENTS

Autonomy is by far our biggest contributor to industry
Using Arduino to control motors
Using timing delays to simulate real world application of GPS

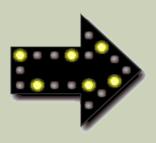
2. SERVICEABILITY AND ROTATION LIMIT



MARGARET GIDULA

SERVICEABILITY AND ROTATION LIMIT

- Assume Rigid Body
- Measured from top of tower to water level
- Our wind turbine will not tilt more than 10°



SIGNIFICANTLY GREATER THAN CODE, WHY?

- No code exists for floating turbines
- Floating allows for more flexibility

MARGARET GIDULA

3. POWER EFFICIENCY

- After construction of the prototype we will be measuring efficiency of Land vs Sea
- Basic objective is to make power
- Output on sea as close to equal as possible





CONCLUSIONS

Biggest contributor to market is Autonomy

Our three factors of focus are:

- Efficiency
- Deflection Limit
- Stationary Location Radius



FUTURE WORK PLANS

Assembly & Programming Testing & Modeling Final Procurement

STEPHEN DAVIS

FUTURE WORK PLANS

- Overall on schedule
- Programming is almost complete just
- Waiting on parts to test
- Parts should be in by the end of the week
- Construction will begin next week



JASON DAVIS

FUTURE WORK PLANS

Schedule & Gantt Chart

- About 1 week behind schedule
- 75% under budget

