# Concept Generation and Selection

Team 14 Turbine Blade Handling with TECT Power

> Patrick Filan Clint Kainec John Kemp

### Introduction

#### **TECT Power**

- A turbine part manufacturing facility
- Currently process a variety of turbine blades
- Located in Thomasville, Georgia
- Objective Come up with a design that will remove manual lifting from their processing of a 68K blade.



# **Project Focus**

- Safety
- Modify current cart
- Orientation and 3D position of the blade
- Load and unload
- Machine friendly
- Efficient
- Cost affective



# **Existing Apparatus**

#### **Previous Team**

- Cart design
- Transport from storage to machine 1
- Orientated horizontally
- Many machines

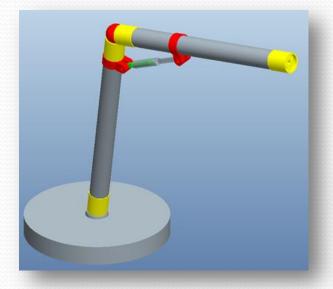


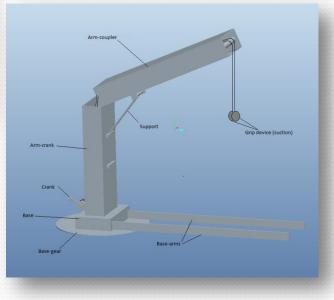
# **Modifications Necessary**

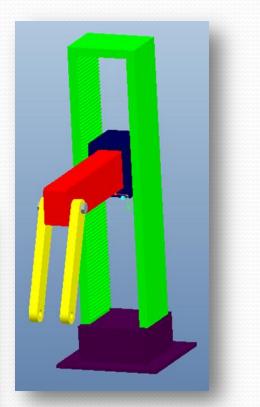
- Cart stability
- Additional mass to the base of the cart
- Blade orientation
- Rigid grip of blade
- Cart maneuverability
- Altercation of current tray carrier



### Part 1 – Arm Apparatus

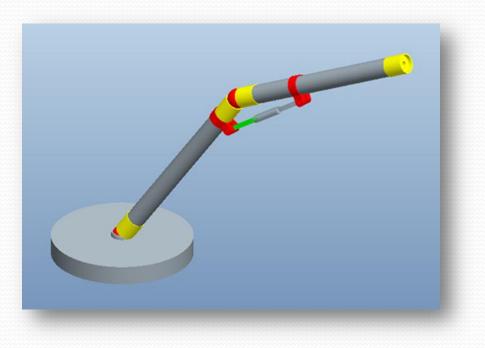






# Design 1 – Ball-Joint Arm

- Autonomous assembly lines
- Two rigid arms connected by a ball joint
- Hydraulic damper
- Spring
- Power screw
- Allows for a large degree of freedom
- Reach below itself and extend outwards



# Design 1 – Ball-Joint Arm

#### Pros

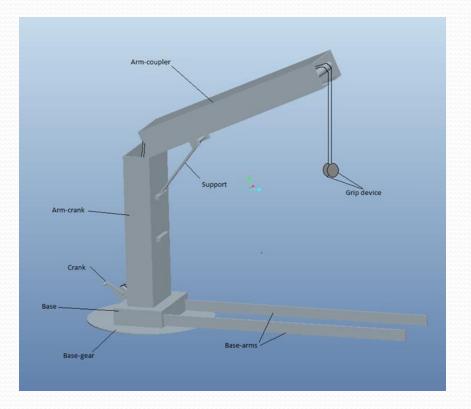
- Capable of large reach
- Capable of reaching below itself
- Natural design (human likearm)
- Easily Adjustable
- Compactable

#### Cons

- Potentially expensive components
- Low durability
- May not reach certain positions
- May be difficult to calibrate
- Replacement of parts

# Design 2 – Pulley System Crane

- Mechanical advantage
- Pulley system
- Arm-coupler angle
- Rotation about the vertical axis via base-gear
- Individual control of each grip with crank



# Design 2 – Pulley System Crane

#### Pros

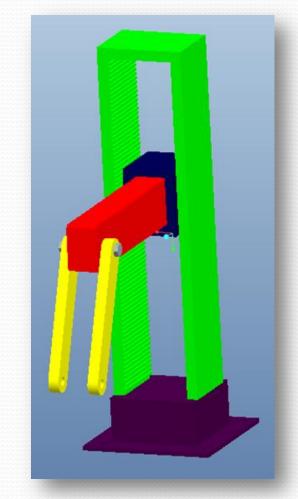
- Mechanical lifting mechanism-Cost
- Durable
- 4 degrees of Freedom
- Multiple blade orientations can be achieved
- Can lift blades from floor

#### Cons

- Suction may be difficult to achieve on an oiled surface
- Fairly slow lifting process
- Possibly difficult self operation

# Design 3 – Threaded Track

- Equipped with an elevator like structure
- Locking system will be implemented to allow the blades to rotate
- Properly geared to provide user/motor with ease



# Design 3 – Threaded Track

#### Pros

- Ability to move the blades vertically and horizontally over any objects
- Structural Strength
- Purely mechanical

#### Cons

- Not super compactable
- May be difficult to maneuver blades into machines
- Maintenance

# Part 2 – Grip Apparatus

#### **Form-Fitted**

- Interchangeable
- Dynamic
  - Vacuumed sand
  - Malleable material



#### **Suction Cups**

- Inexpensive
- Effective at 45 lbs.
- Cons
  - Surface
  - Oil



### **Decision Matrix**

	Arm Concent	Cost	Maneuverability	Effectiveness	Efficiency	Safety	Durability	Maintenance	Practicality	Compactability	Machinability	<b>Total Score</b>
	1	3	4	3	3	4	1	3	2	4	3	30
	2	5	3	3	2	4	2	3	2	3	4	31
-	3	3	2	2	2	3	4	2	3	1	2	26

### **Decision Outcome**

- Design 2 Chosen
  - Cheap
    - Machine most parts
  - Simple design
    - Expandable
  - User-friendly
- Grips will be decided by remaining budget and modifications made to the arm design

## References

- Amend, John. "Sandbagged robotics." 12 January 2011. *Through the Sand and Glass*. Image. October 2012.
- Newton, Jason, et al. "TECT." n.d. *Team* 9. October 2012. <a href="http://eng.fsu.edu/me/senior\_design/2012/team9/">http://eng.fsu.edu/me/senior\_design/2012/team9/</a>>.
- "Spring 2006 Issue 01." n.d. *Robot Magazine*. Image. October 2012. <a href="http://www.botmag.com/issue2/images/bottom2.jpg">http://www.botmag.com/issue2/images/bottom2.jpg</a>>.
- "The Parish of St. Cuthbert with St. Aidan." n.d. Image. 20 October 2012. <a href="http://www.stcuthbertwithstaidan.org.uk/images/IMG\_0721.jpg">http://www.stcuthbertwithstaidan.org.uk/images/IMG\_0721.jpg</a>>.
- <http://www.sciencenewsforkids.org/2010/11/coffee-gives-robots-a-grip/>.
- <http://gizmodo.com/5419292/geeky-gifts-whose-proceeds-go-tocharity/gallery/1>.